



Solving the Navier-Stokes Equations

Chapter 15

Introduction

- For the solution of the scalar equation we have assumed that the velocity field is known

$$\dot{m} = \rho \mathbf{v} \cdot \mathbf{S}$$

- How do we actually compute the velocity field is the subject of this lecture

Velocity Pressure Coupling

Navier-Stokes Equations

$$\underbrace{\frac{\partial(\rho\phi)}{\partial t}}_{\text{transient term}} + \underbrace{\nabla \cdot (\rho \mathbf{v} \phi)}_{\text{convection term}} = \underbrace{\nabla \cdot (\Gamma \nabla \phi)}_{\text{diffusion term}} + \underbrace{Q}_{\text{source term}}$$

Navier-Stokes equations are a special case of the general scalar equation with $\Phi = I, u$ or v and $\Gamma=0$ or μ and appropriate Q

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{v}) = 0$$

$$\frac{\partial(\rho \mathbf{v})}{\partial t} + \nabla \cdot (\rho \mathbf{v} \mathbf{v}) = \nabla \cdot \underline{\tau} - \nabla \underline{p} + \mathbf{B}$$

$$\tau = -\mu(\nabla \mathbf{v} + \nabla \mathbf{v}^T) + \frac{2}{3}\mu \mathbf{I} \nabla \cdot \mathbf{v}$$

NS equations are non-linear

- ▶ Not by itself a problem
- ▶ Can do Picard iteration

Momentum Equations (x,y,z)

- ▶ not a problem
- ▶ Can solve each sequentially

Source terms?

- ▶ stress tensor sources can be computed

Main Issue is that pressure is not known

- ▶ should find a way to compute it
- ▶ what PDE to use?
- ▶ Special case of incompressible flow

Options

- Option 1
 - ▶ Vorticity-Stream function formulation
- Option 2
 - ▶ Density Based formulation
- Option 3
 - ▶ Use the Momentum equations to compute the velocity field
 - ▶ Use the Continuity equation to form a pressure equation to compute the Pressure field
 - ▶ This is known as the Primitive Variables Formulation

Option I

- Used in 70's-80's
 - ▶ Derive one PDE for stream function Ψ and one PDE for the single component vorticity in 2D
 - ▶ Eliminates pressure as variable
 - ▶ Only 2 PDE;s as opposed to 3 for primitive variable formulation (u,v,p)
- However no stream function definition in 3D flows
- Vorticity-vector potential formulation in 3D
 - ▶ 6 components (3 for vorticity, 3 vector potential)
 - ▶ Fewer components for primitive variable formulation
- Difficult to derive bc's

Option 2: Density Methods

- Popular in compressible flow community
- (u, v, w, ρ, E) used as unknowns
- Artificial compressibility/preconditioning schemes
- Effectively add some artificial compressibility to enable use of density-based schemes for incompressible flows
- Widely used in aeronautics industry

Option 3: Pressure Methods

- Will focus on pressure-based methods since they are the most widely used in the incompressible flow community.
- At convergence, the solution satisfies the discrete continuity and momentum equations
- Choice of pressure-based/density-based solution technique only governs
 - ▶ whether we get a solution
 - ▶ how fast/cheaply we can get it
 - ▶ how much memory/storage we need

SIMPLE Algorithm

- Semi-Implicit Method for Pressure-Linked Equations
- Proposed by Patankar and Spalding (1972)
- Idea is to start with discrete continuity equation
- Substitute into it the discrete u and v momentum equations
- Discrete momentum equations contain pressure differences
- Hence get an equation for the discrete pressures
- SIMPLE actually solves for a related quantity called the pressure correction

Flow in Pipes

A portion of a water-supply system is shown in the figure below.

The flow rate in a pipe is given by

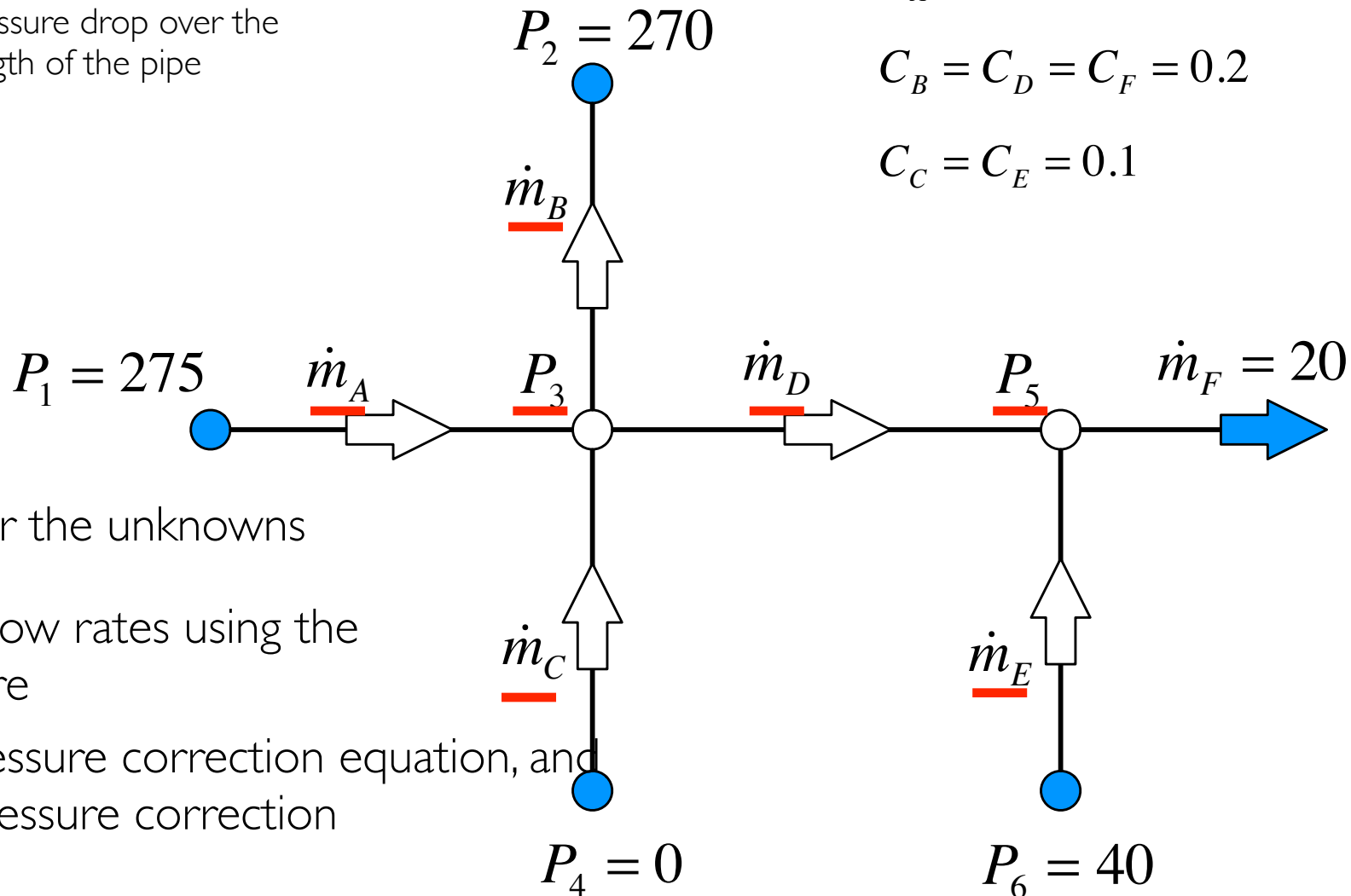
$$\dot{m} = C \Delta P$$

Hydraulic conductance
Pressure drop over the length of the pipe

$$C_A = 0.4$$

$$C_B = C_D = C_F = 0.2$$

$$C_C = C_E = 0.1$$



1

Guess values for the unknowns

2

Compute the flow rates using the guessed pressure

3

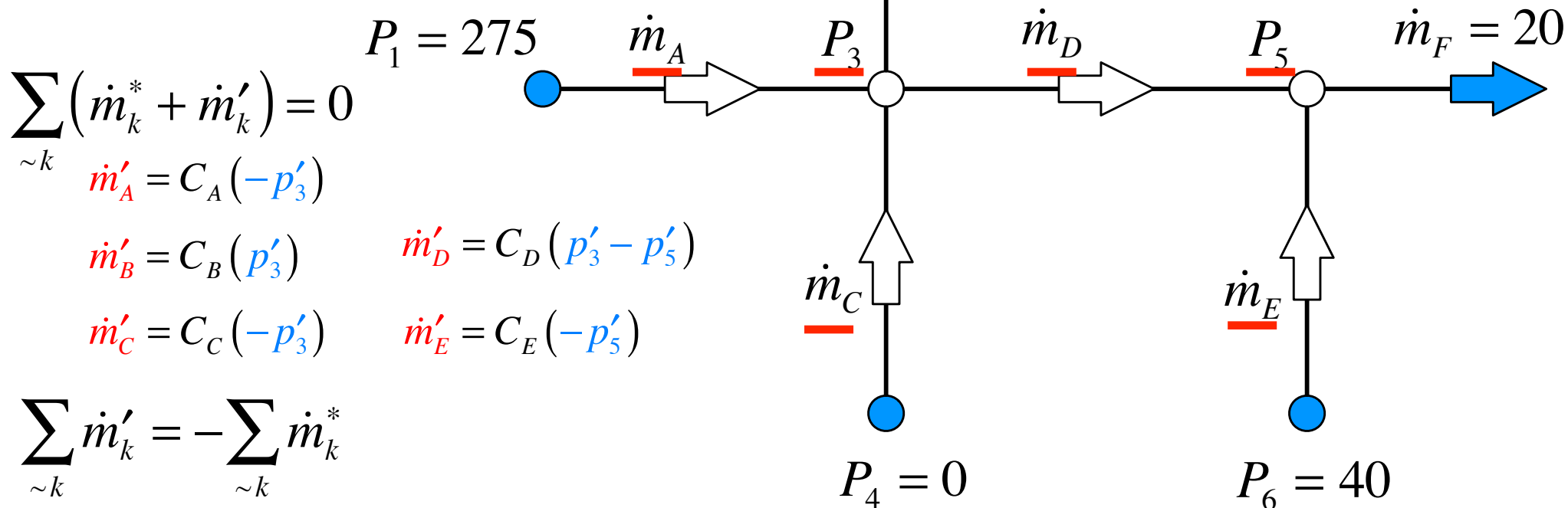
Construct a pressure correction equation, and solve for the pressure correction

Solution

1 $P_3 = 200 \quad P_5 = 30$

2 $\dot{m}_A^* = C_A(P_1 - P_3^*) \quad \dot{m}_B^* = C_B(P_3^* - P_2) \quad \dot{m}_C^* = C_C(P_4 - P_3^*) \quad \dot{m}_D^* = C_D(P_3^* - P_5^*) \quad \dot{m}_E^* = C_E(P_6 - P_5^*)$

3 $\dot{m}^* = C \Delta P^* \rightarrow \sum \dot{m}_k^* \neq 0$
 $\dot{m} = C \Delta P \rightarrow \sum \dot{m}_k = 0$
 $\dot{m}' = C \Delta(P')$



$$\textcircled{3} \sum_{k=nb(3)} (\dot{m}_k^* + \dot{m}_k') = 0$$

$$\textcircled{\circ} \dot{m}'_A - \dot{m}'_B + \dot{m}'_C - \dot{m}'_D = -(\dot{m}_A^* - \dot{m}_B^* + \dot{m}_C^* - \dot{m}_D^*)$$

$$C_A(-p'_3) - C_B(p'_3) + C_C(-p'_3) - C_D(p'_3 - p'_5) = -(\dot{m}_A^* - \dot{m}_B^* + \dot{m}_C^* - \dot{m}_D^*)$$

$$\textcircled{\circ} \dot{m}'_D + \dot{m}'_E = -(\dot{m}_D^* + \dot{m}_E^* - \dot{m}_F)$$

$$C_D(p'_3 - p'_5) + C_E(-p'_5) = -(\dot{m}_D^* + \dot{m}_E^* - \dot{m}_F)$$

$$\sum_{k=nb(5)} (\dot{m}_k^* + \dot{m}_k') = 0$$

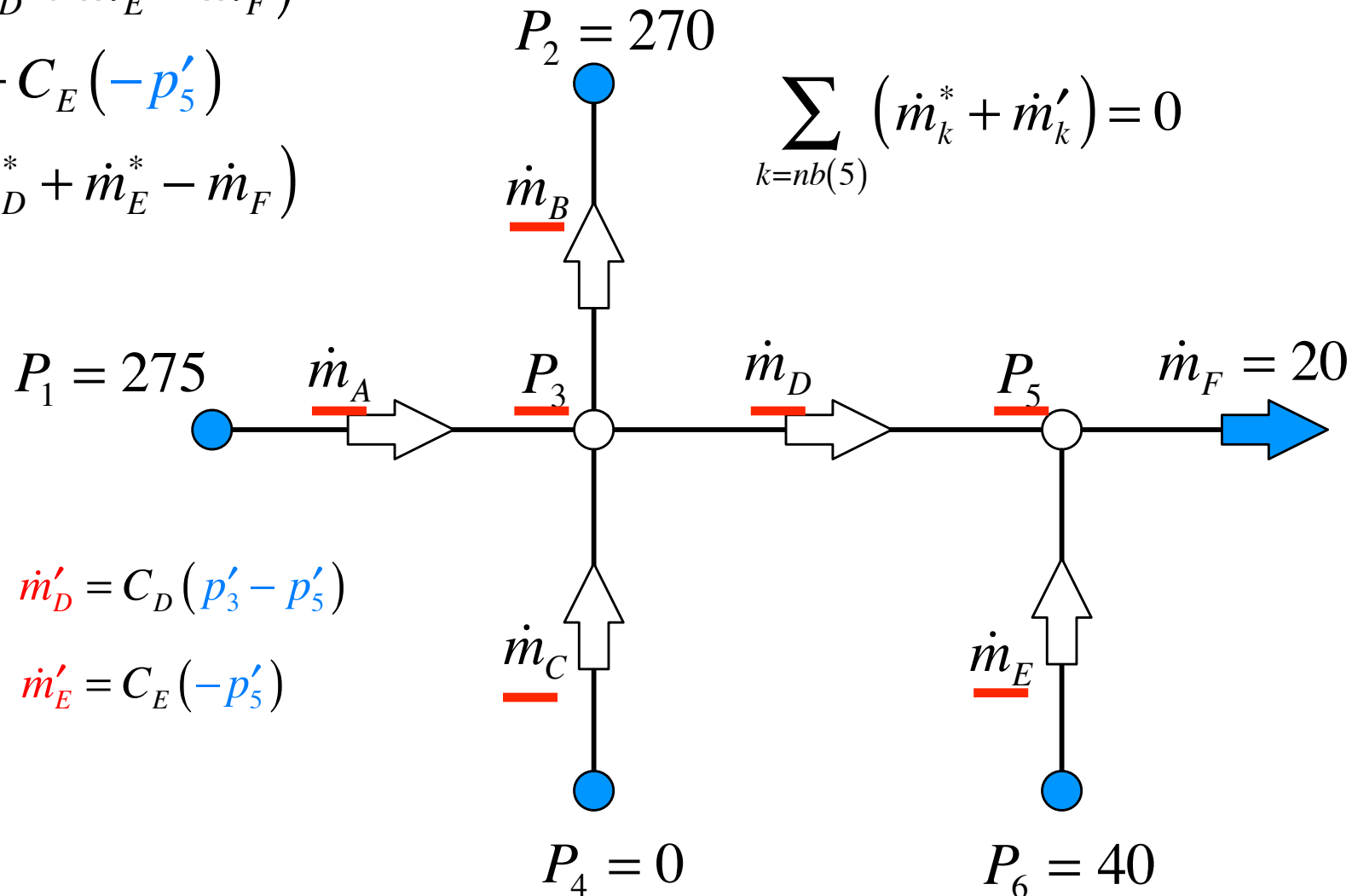
$$\dot{m}'_A = C_A(-p'_3)$$

$$\dot{m}'_B = C_B(p'_3)$$

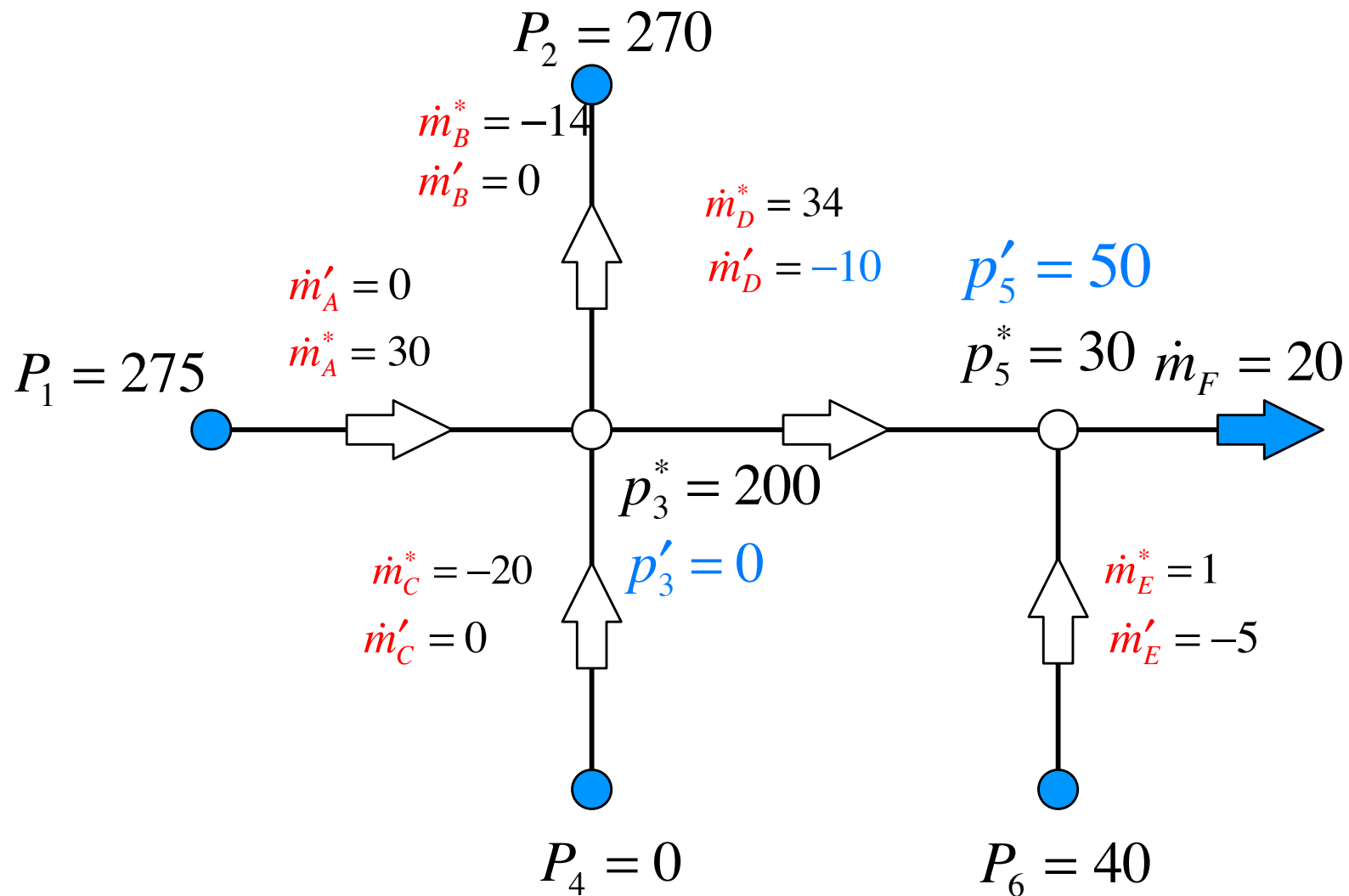
$$\dot{m}'_C = C_C(-p'_3)$$

$$\dot{m}'_D = C_D(p'_3 - p'_5)$$

$$\dot{m}'_E = C_E(-p'_5)$$



$$\begin{aligned} -0.7(p'_3) + 0.2(p'_5) &= 10 \\ 0.2(p'_3) - 0.3(p'_5) &= -15 \end{aligned} \Rightarrow \begin{cases} p'_3 = 0 \\ p'_5 = 50 \end{cases}$$



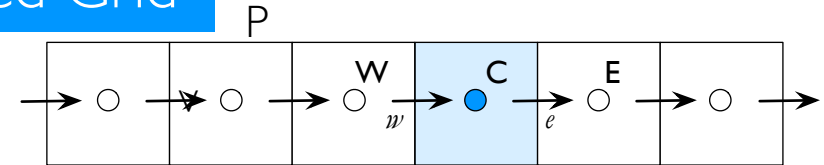
SIMPLE Based Algorithms

The SIMPLE Algorithm

$$\nabla \cdot (\rho \mathbf{v} \mathbf{v}) = -\nabla p + \nabla \cdot \boldsymbol{\tau} + \mathbf{B}$$

$$\nabla \cdot (\rho \mathbf{v}) = 0$$

Staggered Grid



Predictor $^{(n)}, P^{(n)}$

$$a_C^v \mathbf{v}_C^\bullet + \sum_{F=NB(C)} a_F^v \mathbf{v}_F^\bullet = -V_C (\nabla p^{(n)})_C \quad \therefore \mathbf{v}^\bullet, P^{(n)}$$

Corrector P'

$$\sum_{f=nb(C)} \dot{m}_f^\bullet \neq 0 \quad \sum_{f=nb(C)} \dot{m}_f = 0$$

$$\sum_{f=nb(C)} (\dot{m}_f^\bullet + \dot{m}_f') = 0 \quad \begin{aligned} \dot{m}_f^\bullet &= \rho \mathbf{v}_f^\bullet \cdot S_f \\ \dot{m}_f' &= \rho \mathbf{v}_f' \cdot S_f \end{aligned}$$

$$\sum_{f=nb(C)} \dot{m}_f' = - \sum_{f=nb(C)} \dot{m}_f^\bullet$$

$$\rightarrow a_e^u u_e^\bullet + \sum_{f=NB(e)} a_f^u u_f^\bullet = -V_e (\nabla p^{(n)})_e$$

$$\sum_{f=NB(C)} \rho \mathbf{v}_f^\bullet \cdot S_f = \rho u_e^\bullet A_e - \rho u_w^\bullet A_w$$

$$u_e^\bullet + \sum_{f=NB(e)} \frac{a_f^u u_f^\bullet}{a_e^u} = -\frac{V_e}{a_e^u} \left(\frac{\partial p^{(n)}}{\partial x} \right)_e$$

$$u_w^\bullet = H_w(u^\bullet) - d_w \left(\frac{\partial p^{(n)}}{\partial x} \right)_w$$

$$u_e^\bullet = H_e(u^\bullet) - d_e \left(\frac{\partial p^{(n)}}{\partial x} \right)_e$$

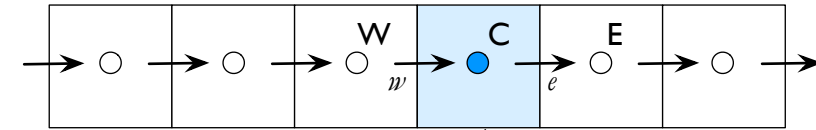
$$u_e' = H_e(u') - d_e \left(\frac{\partial p'}{\partial x} \right)_e$$

$$\mathbf{v}_f' = H_f(\mathbf{v}') - d_f (\nabla p')_f$$

Pressure Equation

$$\sum_{f=nb(C)} \rho \mathbf{v}'_f \cdot \mathbf{S}_f = - \sum_{f=nb(C)} \dot{m}_f \quad \text{Substituting } \mathbf{v}'_f = H_f(\mathbf{v}') - d_f(\nabla p')_f$$

$$\sum_{f=nb(C)} \left[H_f(\mathbf{v}') - d_f(\nabla p')_f \right] \cdot \mathbf{S}_f = - \sum_{f=nb(C)} \dot{m}_f$$



$$\sum_{f=nb(C)} -d_f(\nabla p')_f \cdot \mathbf{S}_f = - \sum_{f=nb(C)} \dot{m}_f - \sum_{f=nb(C)} H_f(\mathbf{v}') \cdot \mathbf{S}_f$$

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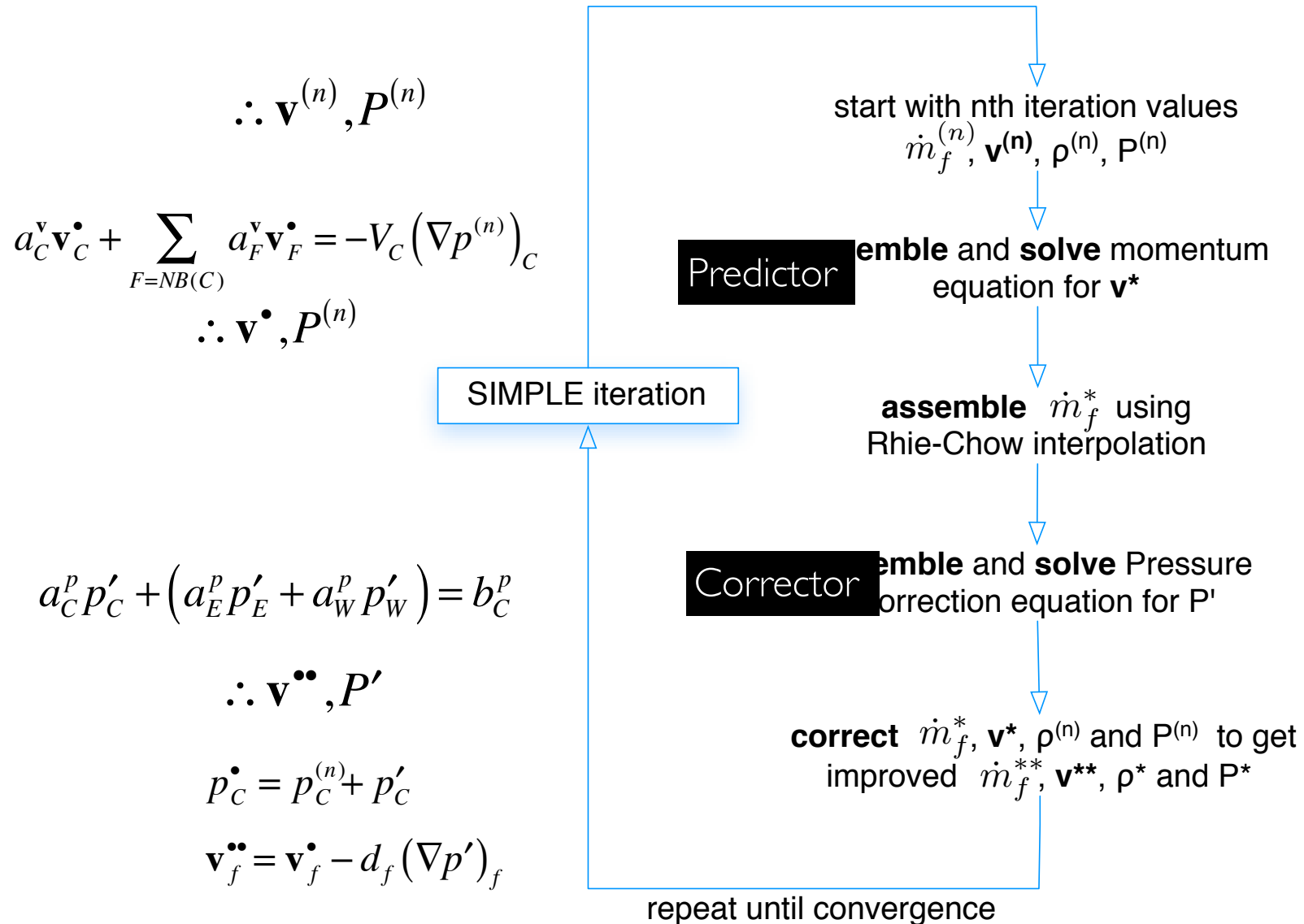
$$\sum_{f=nb(C)} -d_f(\nabla p')_f \cdot \mathbf{S}_f = \sum_{f=nb(C)} -\frac{d_f A_f}{\|CF\|} (p'_F - p'_C) - \sum_{f=nb(C)} \dot{m}_f^{\text{PISO}} = -(\rho u_e \dot{A}_e - \rho u_w \dot{A}_w)$$

$$= a_C^p p'_C + (a_E^p p'_E + a_W^p p'_W)$$

$$\Rightarrow \sum_{f=nb(C)} -\frac{d_f A_f}{\|CF\|} (p'_F - p'_C) = -(\rho u_e \dot{A}_e - \rho u_w \dot{A}_w)$$

$$a_C^p p'_C + (a_E^p p'_E + a_W^p p'_W) = b_C^p \quad \Rightarrow \mathbf{v}'_f = -d_f(\nabla p')_f \quad \Rightarrow \mathbf{v}''_f = \mathbf{v}'_f - d_f(\nabla p')_f$$

The SIMPLE Algorithm



Sequential Solution

- Pressure methods were also developed as sequential methods as opposed to coupled methods where all the Navier-Stokes equations are solved simultaneously
- In sequential methods each of the following equations is solved individually in sequence
 - ▶ Solve u-momentum equation for u velocity component, with all other variables assumed known
 - ▶ Solve v-momentum equation for v velocity component
 - ▶ Modify the continuity equation to yield a pressure equation and solve for pressure
 - ▶ Repeat process until convergence

Collocated Grids

Collocated Grids

$$\sum_{f=nb(C)} \dot{m}'_f = - \sum_{f=nb(C)} \dot{m}_f$$

$$\sum_{f=nb(C)} \rho \bar{\mathbf{v}}'_f \cdot \mathbf{S}_f = - \sum_{f=nb(C)} \dot{m}_f$$

$$\bar{\mathbf{v}}'_f = \frac{1}{2}(\mathbf{v}'_C + \mathbf{v}'_F)$$

$$= \frac{1}{2} \left(H_C(\mathbf{v}') - D_C \left(\frac{\partial p'}{\partial x} \right)_C + H_F(\mathbf{v}') - D_F \left(\frac{\partial p'}{\partial x} \right)_F \right)$$

$$\bar{u}'_e = \bar{H}_e(u') + \bar{D}_e \left(\frac{\partial p'}{\partial x} \right)_e \quad \bar{u}'_w = \bar{H}_w(u') + \bar{D}_w \left(\frac{\partial p'}{\partial x} \right)_w$$

$$\bar{u}'_e - \bar{u}'_w = \bar{H}_e(u') - \bar{H}_w(u') + \bar{D}_e \left(\frac{\partial p'}{\partial x} \right)_e - \bar{D}_w \left(\frac{\partial p'}{\partial x} \right)_w$$

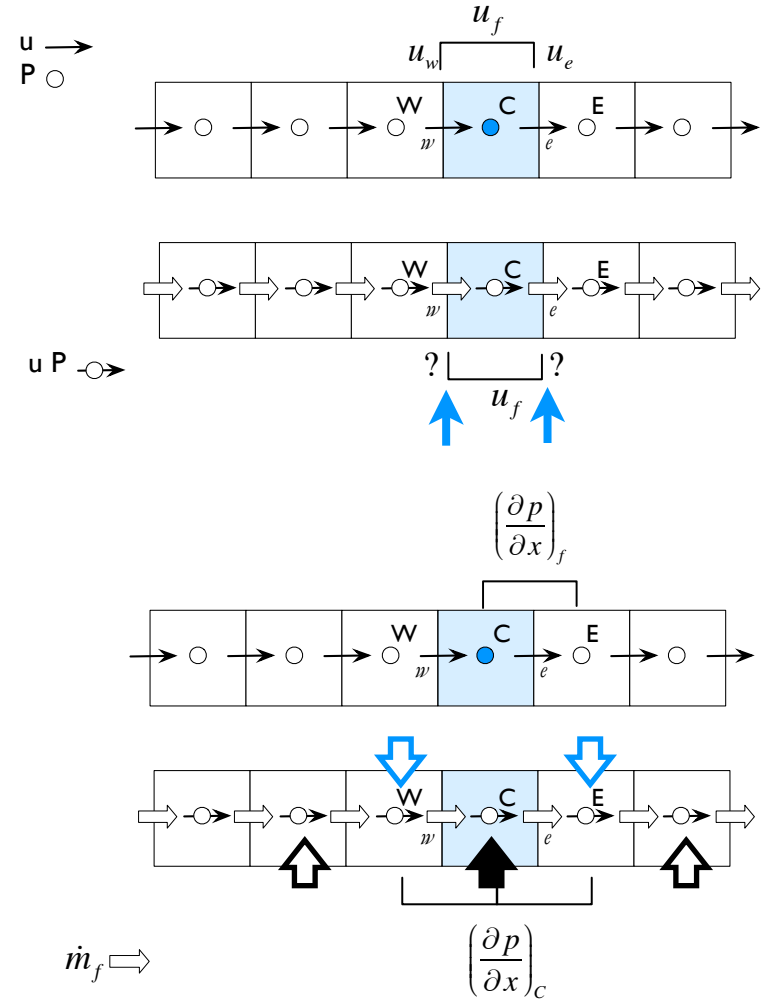
$$\approx D \frac{1}{2} \left[\left(\frac{\partial p'}{\partial x} \right)_E + \left(\frac{\partial p'}{\partial x} \right)_C - \left(\frac{\partial p'}{\partial x} \right)_C - \left(\frac{\partial p'}{\partial x} \right)_W \right]$$

$$\approx \frac{D}{\Delta x} \frac{1}{2} [p'_{EE} - 2p'_C + p'_{WW}]$$

Similarly

$$\dot{m}'_e - \dot{m}'_w = \rho A (u'_E - u'_W)$$

$$a_{CP}^p p'_C + a_{EP}^p p'_{EE} + a_{WP}^p p'_{WW} = -(\dot{m}'_E - \dot{m}'_W)$$



Rhie Chow Interpolation

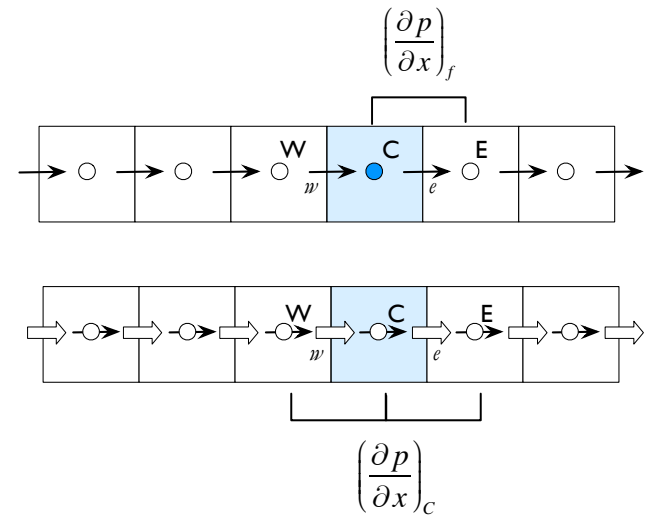
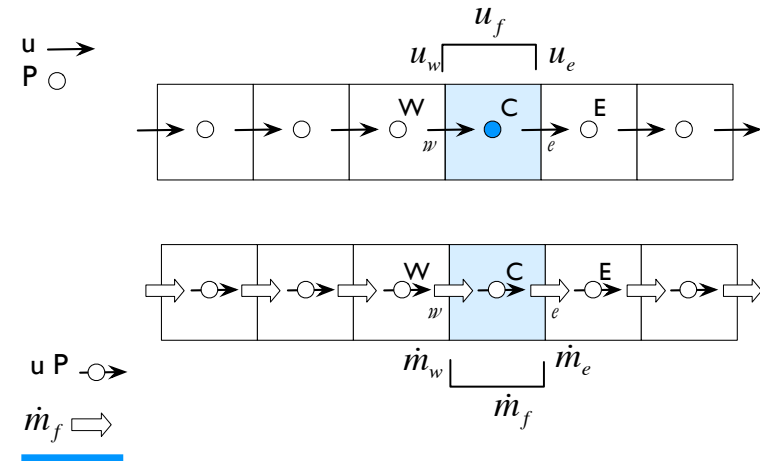
$$\mathbf{v}_P = H_C(\mathbf{v}) - D_C \nabla p_C$$

$$H_P(\mathbf{v}) = - \sum_F \frac{a_F^{\mathbf{v}} \mathbf{v}_F}{a_C^{\mathbf{v}}}$$

$$\mathbf{v}_F = H_F(\mathbf{v}) - D_F \nabla p_F$$

$$D_P = \frac{V_C}{a_C^{\mathbf{v}}}$$

$$\mathbf{v}_f = \overline{H}_f(\mathbf{v}) - \overline{D}_f \nabla p_f$$



$$\begin{aligned} \text{1} \quad \overline{H}_f(\mathbf{v}) &= g_P H_P(\mathbf{v}) + g_F H_F(\mathbf{v}) \\ &= g_P (\mathbf{v}_P + D_P \nabla p_P) + g_F (\mathbf{v}_F + D_F \nabla p_F) \\ &\approx \overline{\mathbf{v}}_f + \overline{D}_f \nabla p_f \end{aligned}$$

$$\overline{D}_f = \frac{\overline{V}_f}{a_f^{\mathbf{v}}}$$

$$\begin{aligned} \text{2} \quad \mathbf{v}_f &= (\overline{\mathbf{v}}_f + \overline{\nabla p}_f) - \overline{D}_f \nabla p_f \\ &= \overline{\mathbf{v}}_f - \overline{D}_f (\nabla p_f - \overline{\nabla p}_f) \end{aligned}$$

$$\text{3} \quad \dot{m}_f = \rho \mathbf{v}_f^{\bullet} \cdot \mathbf{S}_f \quad \dot{m}'_f = \rho \mathbf{v}'_f \cdot \mathbf{S}_f$$

Pressure Correction

$$\sum_{f=nb(C)} \dot{m}'_f = - \sum_{f=nb(C)} \dot{m}_f$$

$$\sum_{f=nb(C)} \rho \mathbf{v}'_f \cdot \mathbf{S}_f = - \sum_{f=nb(C)} \dot{m}_f$$

$$\mathbf{v}'_f = \bar{\mathbf{v}}_f - \bar{D}_f (\nabla p_f - \bar{\nabla} p_f)$$

$$u'_e = \bar{u}'_e - \bar{D}_e \left(\left(\frac{\partial p'}{\partial x} \right)_e - \overline{\left(\frac{\partial p'}{\partial x} \right)}_e \right) \quad u'_w = \bar{u}'_w - \bar{D}_w \left(\left(\frac{\partial p'}{\partial x} \right)_w - \overline{\left(\frac{\partial p'}{\partial x} \right)}_w \right)$$

$$u'_e - u'_w = \left[\cancel{\bar{u}'_e} - \bar{D}_e \left(\left(\frac{\partial p'}{\partial x} \right)_e - \cancel{\overline{\left(\frac{\partial p'}{\partial x} \right)}_e} \right) \right] - \left[\cancel{\bar{u}'_w} - \bar{D}_w \left(\left(\frac{\partial p'}{\partial x} \right)_w - \cancel{\overline{\left(\frac{\partial p'}{\partial x} \right)}_w} \right) \right]$$

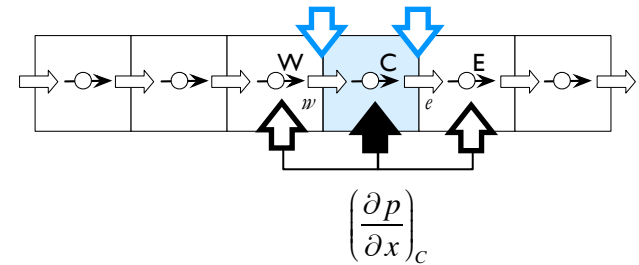
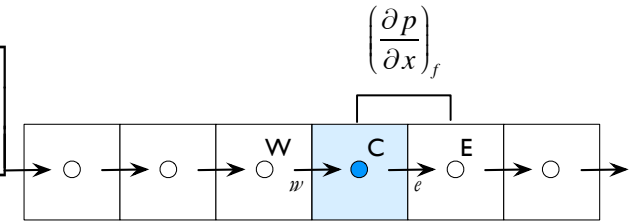
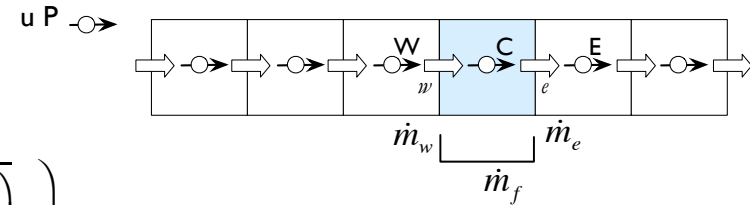
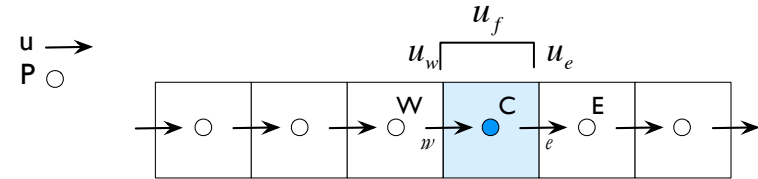
$$\approx D \frac{1}{2} \left[\left(\frac{\partial p'}{\partial x} \right)_e - \left(\frac{\partial p'}{\partial x} \right)_w \right]$$

$$\approx \frac{D}{\Delta x} \frac{1}{2} [p'_E - 2p'_C + p'_W]$$

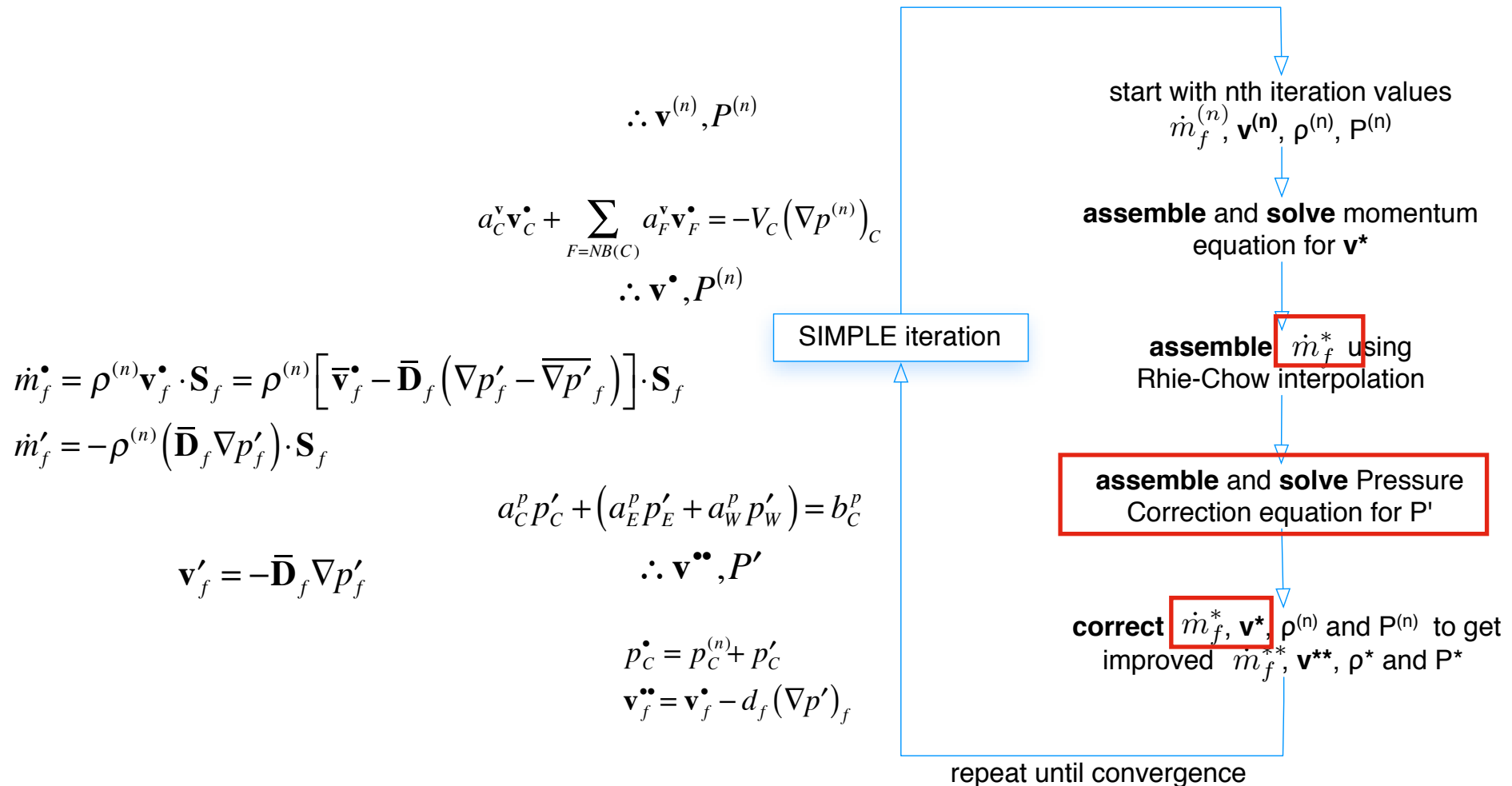
Similarly

$$\dot{m}'_e - \dot{m}'_w = \rho_f u'_e A_e - \rho_w u'_w A_w$$

$$a_C^p p'_C + a_E^p p'_E + a_W^p p'_W = - \sum_{f=nb(C)} \dot{m}_f$$



The Pressure-Correction Equation



Pressure-Velocity Coupling

collocated variable arrangement

Rhie-Chow Interpolation
$$\sum_f (\rho_f^* \bar{D}_f (\nabla P)_f \cdot \mathbf{S}_f) = - \sum_f (\rho_f^* U_f^*) - \underbrace{\sum_f (\rho_f' \mathbf{v}_f' \cdot \mathbf{S}_f)}_{\text{neglected}} - \sum_f (\rho_f^* \mathbf{H}[\mathbf{v}]_f \cdot \mathbf{S}_f)$$

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First Predictor

$$\mathbf{v}_p^* = \mathbf{H}[\mathbf{v}^*]_p - D_p (\nabla P^{(n)})_p$$

First Corrector

$$\begin{aligned} (\mathbf{v}', P', \rho') (\mathbf{v}^{**} &= \mathbf{v}^* + \mathbf{v}', P^* = P^{(n)} + P', \rho^* = \rho^{(n)} + \rho') \\ \mathbf{v}_p^{**} &= \mathbf{H}[\mathbf{v}^{**}]_p - D_p (\nabla P^*)_p = \mathbf{H}[\mathbf{v}^* + \mathbf{v}']_p - D_p [\nabla (P^{(n)} + P')]_p \\ \begin{cases} \mathbf{v}_p' &= \mathbf{H}[\mathbf{v}']_p - D_p (\nabla P')_p \\ \rho' &= C_\rho P' \end{cases} \end{aligned}$$

Condition

$$\begin{aligned} \frac{(\rho_p^* - \rho_p^o)}{\delta t} V + \Delta [\rho^* \mathbf{v}^{**} \cdot \mathbf{S}]_p &= 0 \quad \Leftrightarrow \\ \frac{(\rho_p^{(n)} + \rho_p' - \rho_p^o)}{\delta t} V + \Delta [(\rho^{(n)} + \rho') (\mathbf{v}^* + \mathbf{H}[\mathbf{v}'] - D(\nabla P')) \cdot \mathbf{S}]_p &= 0 \quad \Leftrightarrow \\ \frac{VC_p}{\delta t} P_p' + \Delta [C_\rho U^* P']_p - \Delta [\rho^{(n)} D(\nabla P') \cdot \mathbf{S}]_p &= - \frac{(\rho_p^n - \rho_p^o)}{\delta t} V - \Delta [\rho^{(n)} U^*]_p \\ &\quad - \Delta [\rho^{(n)} \mathbf{H}[\mathbf{v}'] \cdot \mathbf{S}]_p - \Delta [(\rho' \mathbf{v}') \cdot \mathbf{S}]_p \end{aligned}$$

Approximation

Neglect $\mathbf{H}[\mathbf{v}'] \quad \Delta [(\rho' \mathbf{v}') \cdot \mathbf{S}]_p \Rightarrow \mathbf{v}_p' = -D_p (\nabla P')_p$

Approximation Equation

$$\frac{VC_p}{\delta t} P_p' + \Delta [C_\rho U^* P']_p - \Delta [\rho^{(n)} D(\nabla P') \cdot \mathbf{S}]_p = - \frac{(\rho_p^n - \rho_p^o)}{\delta t} V - \Delta [\rho^{(n)} U^*]_p$$

Second Predictor

$$\mathbf{v}_p^{***} = \mathbf{H}^{**}[\mathbf{v}^{**}]_p - D_p^{**} (\nabla P^*)_p$$

Second Corrector

$$\begin{aligned} (\mathbf{v}'', P'', \rho'') (\mathbf{v}^{****} &= \mathbf{v}^{***} + \mathbf{v}'', P^{**} = P^* + P'', \rho^{**} = \rho^* + \rho'') \\ \mathbf{v}_p^{****} &= \mathbf{H}^{**}[\mathbf{v}^{****}]_p - D_p^{**} [\nabla (P^* + P'')]_p \\ \mathbf{v}_p^{***} &= \mathbf{H}^{**}[\mathbf{v}^{**}]_p - D_p^{**} (\nabla P^*)_p \\ \begin{cases} \mathbf{v}_p'' &= \mathbf{H}^{**}[\mathbf{v}^{****} - \mathbf{v}^{**}]_p - D_p^{**} (\nabla P'')_p = \mathbf{H}^{**}[\mathbf{v}^{***} - \mathbf{v}^{**} + \mathbf{v}'']_p - D_p^{**} (\nabla P'')_p \\ \rho'' &= C_\rho P'' \end{cases} \end{aligned}$$

Condition

$$\begin{aligned} \frac{(\rho_p^{**} - \rho_p^o)}{\delta t} V + \Delta [\rho^{**} \mathbf{v}^{****} \cdot \mathbf{S}]_p &= 0 \quad \Leftrightarrow \\ \frac{(\rho_p^* + \rho_p'' - \rho_p^o)}{\delta t} V + \Delta [(\rho^* + \rho'') (\mathbf{v}^{***} + \mathbf{H}^{**}[\mathbf{v}^{***} - \mathbf{v}^{**} + \mathbf{v}''] - D_p^{**} (\nabla P'')) \cdot \mathbf{S}]_p &= 0 \quad \Leftrightarrow \\ \frac{VC_p}{\delta t} P_p'' + \Delta [C_\rho U^{***} P'']_p - \Delta [\rho^* D_p^{**} (\nabla P'') \cdot \mathbf{S}]_p &= - \frac{(\rho_p^* - \rho_p^o)}{\delta t} V - \Delta [\rho^* U^{***}]_p \\ &\quad - \Delta [\rho^* \mathbf{H}^{**}[\mathbf{v}^{***} - \mathbf{v}^{**} + \mathbf{v}''] \cdot \mathbf{S}]_p - \Delta [(\rho'' \mathbf{v}'') \cdot \mathbf{S}]_p \end{aligned}$$

Approximation

Neglect $\mathbf{H}^{**}[\mathbf{v}^{***} - \mathbf{v}^{**} + \mathbf{v}''] \quad \Delta [(\rho'' \mathbf{v}'') \cdot \mathbf{S}]_p \Rightarrow \mathbf{v}_p'' = -D_p^{**} (\nabla P'')_p$

Approximation Equation

$$\frac{VC_p}{\delta t} P_p'' + \Delta [C_\rho U^{***} P'']_p - \Delta [\rho^* D_p^{**} (\nabla P'') \cdot \mathbf{S}]_p = - \frac{(\rho_p^* - \rho_p^o)}{\delta t} V - \Delta [\rho^* U^{***}]_p$$

treatment leads
to variety of schemes

Problem I - Staggered Grid

- Use the SIMPLE procedure to compute p_2 , u_B , and u_C from the following data:

$$\Delta x = 2, c_B = 0.25, c_C = 0.2$$

$$A_B = 5, A_C = 4, p_1 = 200, p_3 = 38$$

- As an initial guess, set

$$u_B = u_C = 15 \text{ and } p_2 = 120$$

